

Aggregate and import SEG-2 borehole receiver spreads & filter traces & run Smooth invert for Shear-Wave crosshole line TEST_1 Rayfract® 5.02 Nov 2025 :

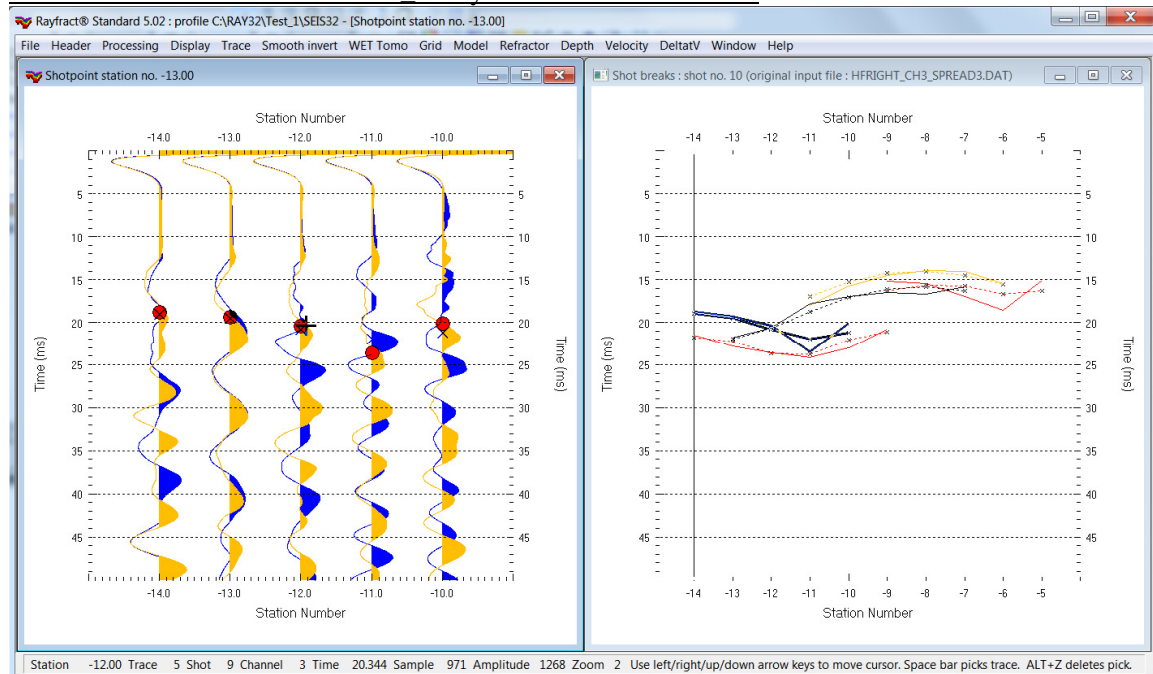


Fig. 1 : Left : Trace/Shot point gather, right : Refractor/Shot breaks. Shows fit between picked times (solid curve, red circles) and modeled times (dashed curve, blue crosses) after 100 WET iterations (Fig. 23).

To create the profile database, aggregate the SEG-2 borehole receiver channels, import the aggregated .DAT spread files and view the imported aggregated .DAT shear-wave shots do these steps :

1. **File>New Profile...**, set **File name** to **TEST_1** and click **Save**. See our manual (Rohdewald 2025).
2. in the prompt shown next (Fig. 4) click **No** button .
3. in **HeaderProfile...** set **Line type** to **Borehole spread/line** . Set **Station spacing** to 1.0m. See Fig. 2.
4. unzip archive https://rayfract.com/tutorials/TEST_1.zip with **SEG-2** .DAT receiver channel files & files **COORDS.COR** & **SHOTPTS.SHO** & **BREAKS.LST** in profile directory **c:\RAY32\TEST_1**
5. download installer <https://rayfract.com/tools/SEG2HoleMerge.exe> and run on your PC where you are running your Rayfract® version 5.02 Standard or Pro license.
6. open **SEG2 HoleMerge 5.02** program via desktop icon . See Fig. 5 .
7. click on file icon besides uppermost field **Select one SEG-2 file in INPUT directory**
8. navigate into **c:\RAY32\TEST_1\5-Left**. At right bottom of dialog select **SEG-2 files (*.DAT)** .
9. click on one file e.g. **5HFLleft.DAT** (receiver channels for elevation -5.0) and click **Open** button
10. set field **Select output directory** to **c:\RAY32\Test_1\5Left**
11. in frame **Determine geophone channel number to be merged** click radio button **S-wave horizontal channel 3/y**. See Fig. 5.
12. in frame **Distance unit : meters or feet** click radio button **Meters**
13. in frame **Determine aggregated receiver geometry for vertical borehole** set **Deepest receiver depth below topo [m]** to 9. Set next field **Receiver spacing [m]** to 1. See Fig. 5.
14. in frame **Determine source position : horizontal and vertical offset from top of hole** set **Source x offset from top-of-hole [m]** to 12.98. Set **Source depth below top-of-hole [m]** to 5.0.
15. click button **Aggregate SEG-2 files**. Confirm prompts (Fig. 6). Click **Close** button.
16. the aggregated SEG-2 receiver spread file **HFLleft_ch3_Spread3.DAT** is written into folder **c:\RAY32\TEST_1\5Left** .
17. repeat steps 6. to 16 for **c:\RAY32\TEST_1\5-Right\5HFRright.DAT**. See Fig. 9. In step 8. navigate into **c:\RAY32\TEST_1\5-Right** . In step 9. select **5HFRright.DAT**. In step 10. set field **Select output directory** to **c:\RAY32\Test_1\5Right**. See Fig. 9. In step 16. the aggregated SEG-2 file **HFRright_ch3_Spread3.DAT** is written into folder **c:\RAY32\TEST_1\5Right** .
18. click on title bar of our opened Rayfract® 5.02
19. check import option **File\SEG-2 import settings and commands\Receiver coordinates specified**

20. select **File|Import Data...** . Set *Import data type* to **SEG-2**. See Fig. 3.
21. click **Select** button and navigate into **C:\RAY32\TEST_1\5Left**
22. leave *Files of type* at **SEG-2 files (*.DAT)** and select file **HFLeft_ch3_Spread3.DAT** & click **Open**
23. click **Import shots** button and confirm prompt
24. in Fig. 7 click **Skip** button to skip all other .DAT spread files in the same input directory until the title caption says **Import C:\RAY32\TEST_1\5LEFT\HFLEFT_CH3_SPREAD3.DAT**.
25. set **Shot Number** to 1 and click **Read** button. Next click **End** button to end the import session.
26. reselect **File|Import Data** (Fig. 3). Click **Select** button and navigate into **C:\RAY32\TEST_1\5Right** .
27. leave *Files of type* at **SEG-2 files (*.DAT)** and select file **HFRight_ch3_Spread3.DAT** & click **Open**
28. click **Import shots** button and confirm prompt
29. in Fig. 7 click **Skip** button to skip all other .DAT spread files in the same input directory until the title caption says **Import C:\RAY32\TEST_1\5RIGHT\HFRIGHT_CH3_SPREAD3.DAT**.
30. set **Shot Number** to 2 and click **Read** button. Next click **End** button to end the import session.
31. select **Trace|Shot point gather** and **Refractor|Shot breaks** and **Window|Tile** to obtain Fig. 1
32. click on title bar of **Refractor|Shot breaks** window (Fig. 1 right). Press **ALT+P**. Edit *Maximum time* to 50 ms. Press **ENTER** key to redisplay. Do the same for **Trace|Shot point gather** window (Fig. 1 left).
33. click on title bar of **Trace|Shot point gather** window and press **CTRL+F1** to zoom trace amplitude
34. press **CTRL+F3** to toggle trace wiggle display mode. Uncheck **Display|Color trace outline**.
35. press **SHIFT+Q** and edit *Band pass filter* as in Fig. 8 . Click **Filter** button.
36. select **Processing|Pick all shots, in shot point gather**.
37. select **Display|Show picks on time axis**.

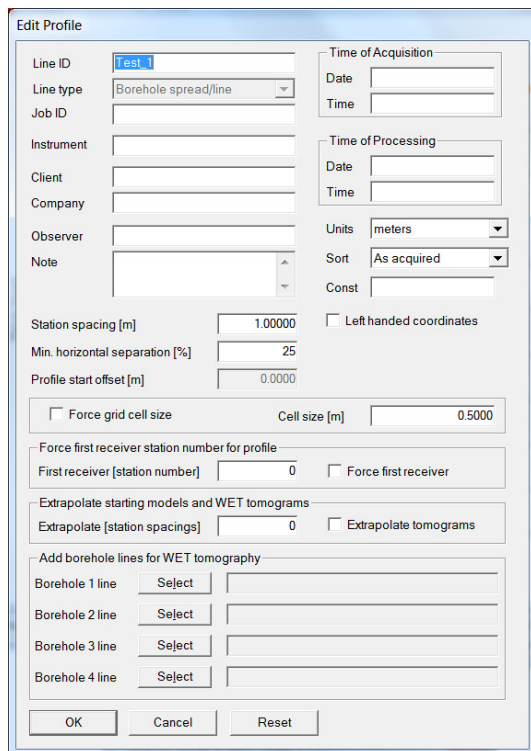


Fig. 2 : Header|Profile

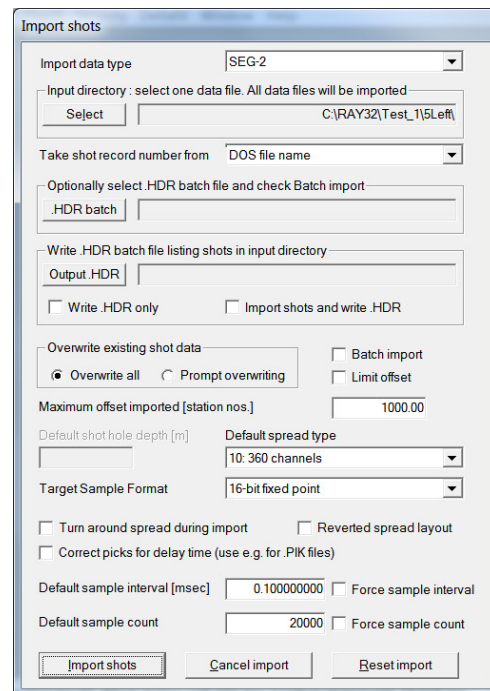


Fig. 3 : File|Import Data

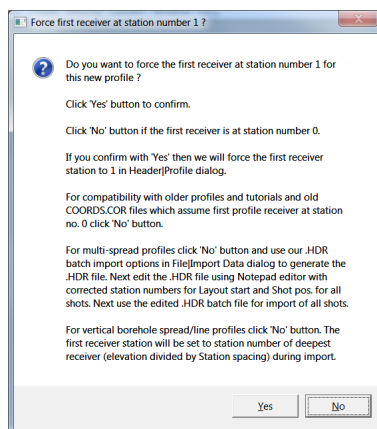


Fig. 4 : click No button.

For vertical borehole/spread line profiles click 'No' button. The first receiver station will be set to station number of deepest receiver (elevation divided by *Station spacing*) during import.

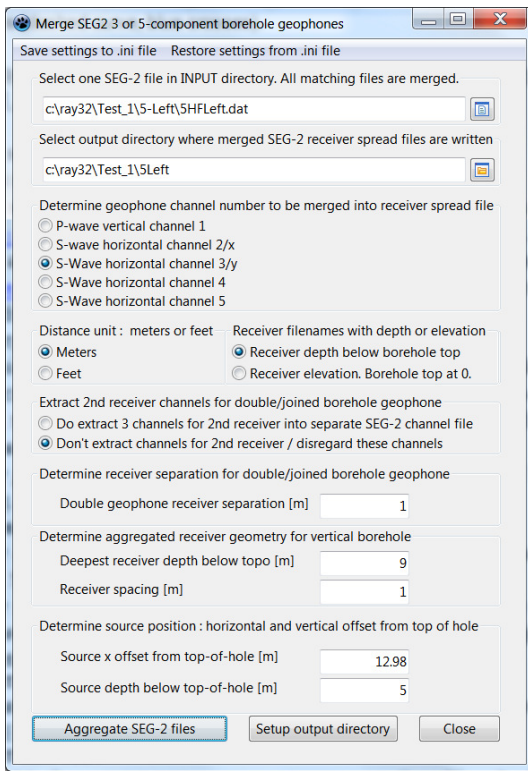


Fig. 5 : click SEG2 HoleMerge 5.02 icon. Edit as shown. Click button **Aggregate SEG-2 files**.

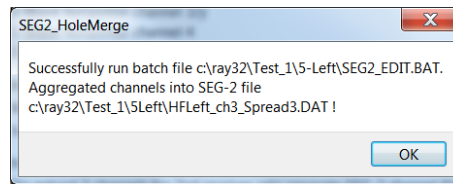


Fig. 6 : prompt shown after clicking button **Aggregate SEG-2 files**. Click OK to dismiss.

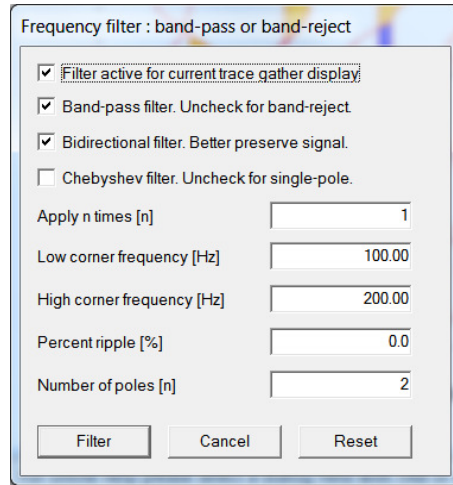


Fig. 8 (above) : Band-pass filter dialog shown with SHIFT+Q. Edit as shown and click **Filter button**.

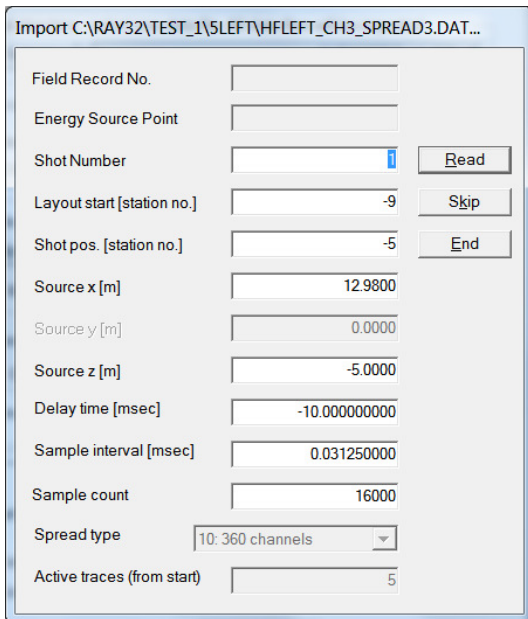


Fig. 7 : *Import Shot dialog* shown when clicking **Import Shots** in *File/Import Data* (Fig. 3). Skip all other .DAT spread files in the same input directory with click on **Skip button** until the dialog caption says HFLEFT_CH3_SPREAD3.DAT . Now set **Shot Number** to 1 and click **Read** button. Next if necessary click **End button** to end the import session.

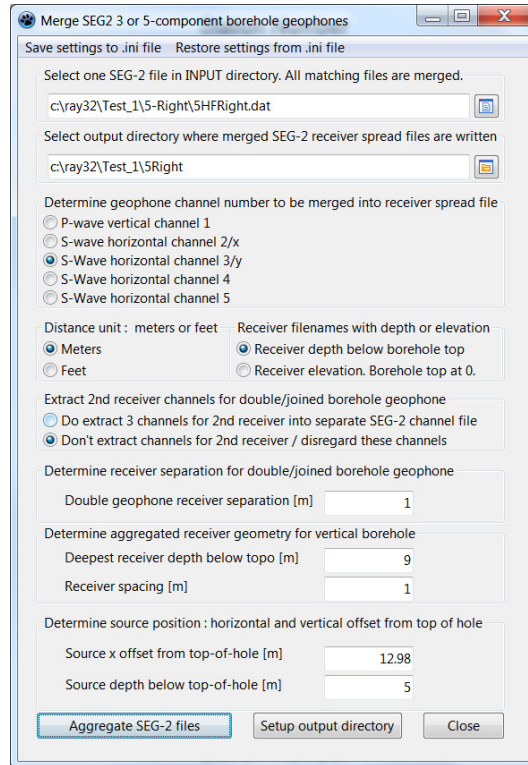


Fig. 9 : click SEG2 HoleMerge 5.02 icon. Edit as shown. Click button **Aggregate SEG-2 files**.

38. press ALT+Q and edit *High-pass filter* as shown in Fig. 10. Click *Filter* button.

39. press ALT+M and edit *Trace processing parameters* as in Fig. 11. Click *Filter* button.

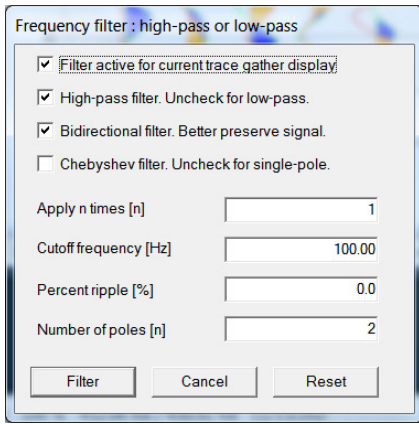


Fig. 10 (left) : High-pass filter dialog shown with ALT+Q. Edit as shown and click **Filter button**.

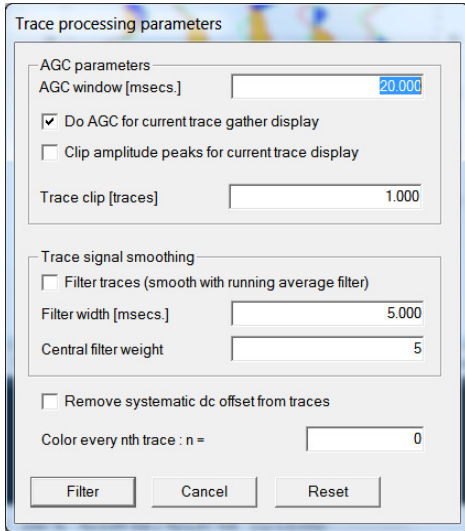


Fig. 11 : Trace processing parameters dialog shown with ALT+M. Edit as shown and click **Filter button**.

Input folder	Input file	Output folder	Deepest receiver depth below top [m]	Source depth below top [m]
5-Left	5HFLeft.dat	5Left	9	5
5-Right	5HFRight.dat	5Right	9	5
7-Left	6HLeft.dat	7Left	11	7
7-Right	6HFRight.dat	7Right	11	7
9-Left	7HFLeft.dat	9Left	13	9
9-Right	7HFRight.dat	9Right	13	9
11-Left	9HFLeft.dat	11Left	14	11
11-Right	9HFRight.dat	11Right	14	11
13-Left	10HFLeft.dat	13Left	14	13
13-Right	10HFRight.dat	13Right	14	13

Fig. 12 : repeat steps 6. to 16 for input folders shown in first column. In SEG2_HoleMerge program (Fig. 5) in topmost frame **Input directory** navigate into input folder and select the input file shown in 2nd column. Edit **Output directory** as shown in 3rd column. Edit **Deepest receiver depth below topo [m]** as in 4th column. Edit **Source depth below top-of-hole [m]** as in 5th column. Click **Aggregate SEG-2 files button** to obtain the aggregated receiver spread file named **HFLeft_ch3_spread3.DAT** or **HFRight_ch3_spread3.DAT** in the output folder.

40. repeat steps 6. to 16. for the remaining input folders 7-Left to 13-Right shown in first column of table in Fig. 12 as in below steps :
41. in SEG2_HoleMerge program (Fig. 5) in topmost frame **Input directory** navigate into input folder and select the input file shown in 2nd column of Fig. 12
42. edit **Output directory** as shown in 3rd column of Fig. 12
43. edit **Deepest receiver depth below topo [m]** as in 4th column of Fig. 12
44. edit **Source depth below top-of-hole [m]** as in 5th column of Fig. 12
45. click **Aggregate SEG-2 files button** (Fig. 5) to obtain the aggregated receiver spread file named **HFLeft_ch3_spread3.DAT** or **HFRight_ch3_spread3.DAT** in the output folder

Input directory	Input spread file	Shot Number	Layout start [station]	Shot pos. [station]
C:\Ray32\Test_1\5Left	HFLleft_ch3_spread3.dat	1	-9	-5
C:\Ray32\Test_1\5Right	HFRright_ch3_spread3.dat	2	-9	-5
C:\Ray32\Test_1\7Left	HFLleft_ch3_spread3.dat	3	-11	-7
C:\Ray32\Test_1\7Right	HFRright_ch3_spread3.dat	4	-11	-7
C:\Ray32\Test_1\9Left	HFLleft_ch3_spread3.dat	5	-13	-9
C:\Ray32\Test_1\9Right	HFRright_ch3_spread3.dat	6	-13	-9
C:\Ray32\Test_1\11Left	HFLleft_ch3_spread3.dat	7	-14	-11
C:\Ray32\Test_1\11Right	HFRright_ch3_spread3.dat	8	-14	-11
C:\Ray32\Test_1\13Left	HFLleft_ch3_spread3.dat	9	-14	-13
C:\Ray32\Test_1\13Right	HFRright_ch3_spread3.dat	10	-14	-13

Fig. 13 : select the aggregated receiver spread file (2nd column) in input directory (column 1) in **File\Import Data** (Fig. 3) with **Select button**. Click button **Import shots**. In *Import Shot dialog* (Fig. 7) skip all other .DAT spread files with **Skip button** until the dialog title shows the input spread file for channel 3 as shown in 2nd column. Now edit the **Shot Number** to value shown in 3rd column. Leave **Layout start [station no.]** and **Shot pos. [station no.]** at station numbers shown in 4th and 5th column. Click **Read button**. Skip all other .DAT spread files in same input directory with **End button** if necessary.

46. import the remaining shot numbers 3 to 10 listed in Fig. 13 column 3 using **File\Import Data** (Fig. 3) as follows :
47. in **File\Import Data** (Fig. 3) click **Select button**. Navigate into input directory (first column in Fig. 13) and select the input spread file **HFLleft_ch3_spread3.dat** or **HFRright_ch3_spread3.dat** (2nd column in Fig. 13).
48. click button **Import shots**. In *Import Shot dialog* (Fig. 7) skip all other .DAT spread files in same input directory with **Skip button** until the dialog title shows the input spread file for channel 3 shown in 2nd column.
49. edit **Shot Number** to value shown in 3rd column (Fig. 13)
50. leave **Layout start [station no.]** at station number shown in 4th column (Fig. 13)
51. leave **Shot pos. [station no.]** at station number shown in 5th column (Fig. 13)
52. click **Read button**. Skip all other .DAT spread files in same input directory with **End button** if necessary.
53. repeat above steps 47. to 52. for all remaining shot numbers 3 to 10 listed in Fig. 13.
54. select **File\Update header data\Update First Breaks** and **BREAKS.LST** to update the first break picks for all imported shot numbers.
55. select **Trace\Shot point gather** and **Refractor\Shot breaks** and **Window\Tile** to obtain Fig. 1
56. click on title of *Shot point gather* (Fig. 1 left) and use F7/F8 keys to browse the **Shotpoint station** displayed in the window's title. This is the same station number as listed in 5th column in Fig. 13.

Configure and obtain constant-velocity starting model and run Smooth WET inversion (Rohdewald 2025) :

- edit *Grid\Surfer plot Limits* as in Fig. 14
- select *Model\WDVS Smoothing*. Click radio button **restore WET smoothing** (Fig. 15). Click *OK*.
- check *Grid\Vertical plot title*. Check *Grid\GS CENTERED FONT* to fix Surfer 11 plot display.
- select **Smooth invert\WET with constant-velocity initial model**
- wait for the constant-velocity starting model to show as in Fig. 16
- in prompt to continue with WET inversion click *Yes* button to obtain Fig. 17 and Fig. 18

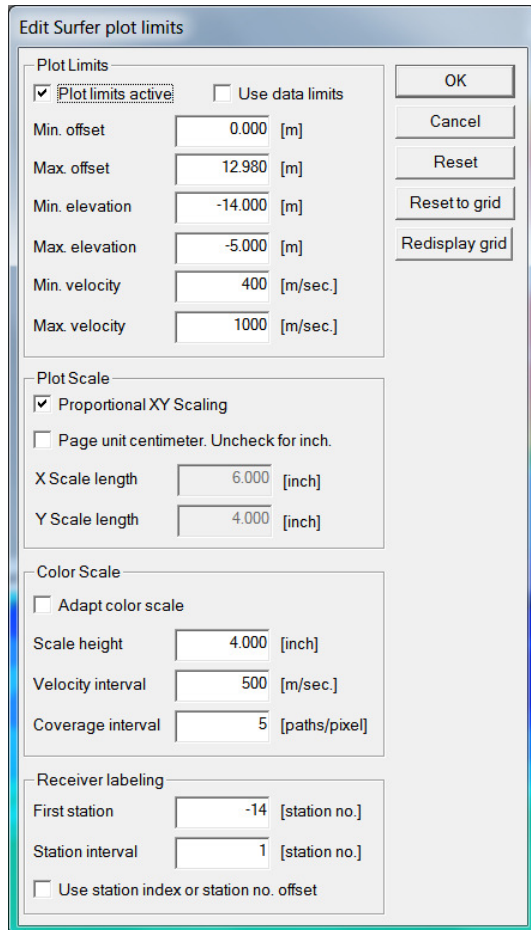


Fig. 14 : *Grid\Surfer plot Limits* dialog. Check box **Limits active** and **Proportional XY scaling**. Edit as shown. Click OK button.

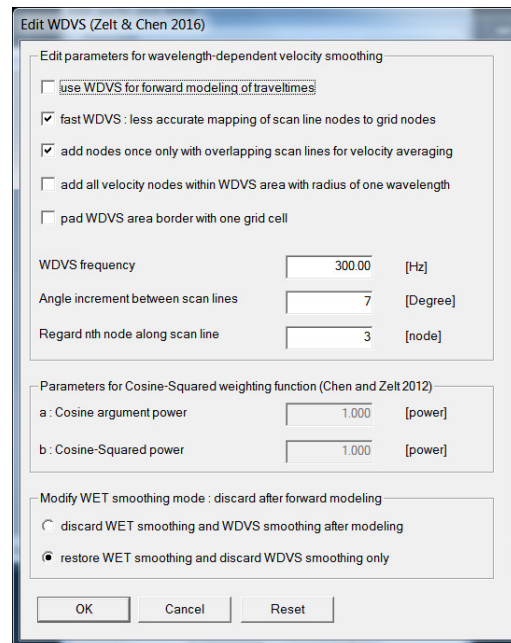


Fig. 15 : *Model\WDVS Smoothing* dialog. Click option **restore WET smoothing discard WDVS smoothing only**. Click OK button.

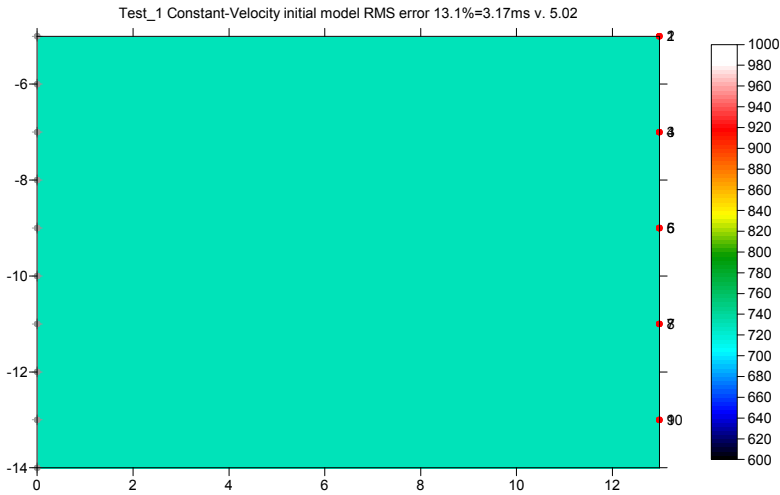


Fig. 16 : Constant-velocity starting model obtained with **Smooth invert/WET with constant-velocity initial model**. Confirm prompt to continue with 2D WET inversion (Schuster 1993) to obtain Fig. 17 & 18.

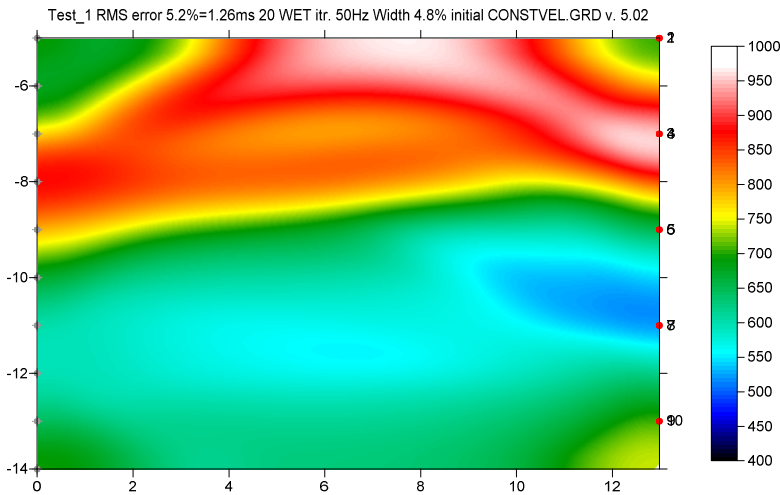


Fig. 17 : default WET tomogram (Schuster 1993) obtained with **Smooth invert/WET with constant-velocity initial model** and starting model shown in Fig. 16.

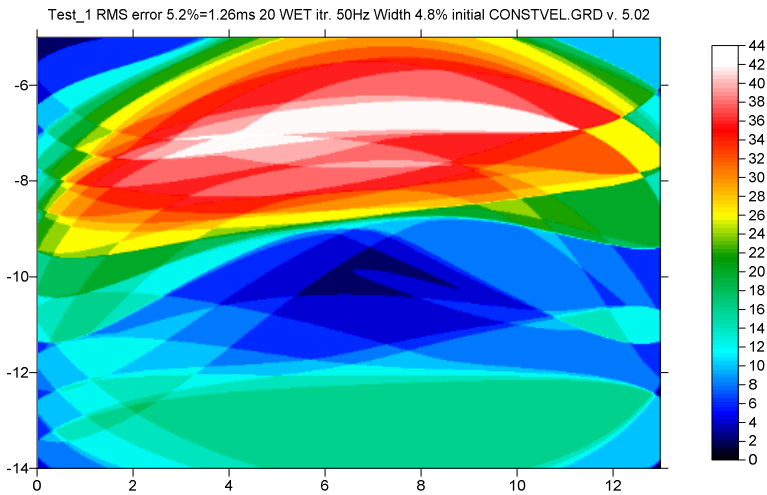


Fig. 18 : WET wavepath coverage plot obtained with Fig. 17. Unit is wavepaths per grid cell.

Interactive WET inversion of crosshole shear-wave first breaks using optimized WET settings :

Next we show optimized WET inversion (Schuster 1993, Rohdewald 2025) :

- select *Header|Profile*. Check box *Force grid cell size*. Set *Cell size[m]* to 0.02. Click *OK* button. See Fig. 19.
- select *Model|WDVS Smoothing*. Check box *discard WET smoothing and WDVS smoothing after modeling*. Leave box *use WDVS for forward modeling of traveltimes* unchecked. Click *OK* button. See Fig. 20.
- select *Grid|Surfer plot Limits*. Edit velocity range as shown in Fig. 21. Click *OK* button.
- select *WET Tomo|Interactive WET tomography*.
- set *Number of WET tomography iterations* to 100. See Fig. 22 (left).
- click button *Edit velocity smoothing*. Click buttons *Reset parameters* and *Accept parameters*. See Fig. 22 (right).
- click button *Start tomography processing* to obtain Fig. 23 and Fig. 24

The 'Edit Profile' dialog box contains the following fields and options:

- Line ID: Test_1
- Line type: Borehole spread/line
- Job ID: (empty)
- Instrument: (empty)
- Client: (empty)
- Company: (empty)
- Observer: (empty)
- Note: (empty)
- Station spacing [m]: 1.00000
- Min. horizontal separation [%]: 25
- Profile start offset [m]: 0.0000
- Force grid cell size, Cell size [m]: 0.0200
- Force first receiver station number for profile: First receiver [station number]: 0, Force first receiver
- Extrapolate starting models and WET tomograms: Extrapolate [station spacings]: 0, Extrapolate tomograms
- Add borehole lines for WET tomography: Borehole 1 line, Borehole 2 line, Borehole 3 line, Borehole 4 line (each with a 'Select' button and an empty text field)
- Buttons: OK, Cancel, Reset

Fig. 19 : select *Header|Profile*. Check box *Force grid cell size*. Set *Cell size[m]* to 0.02. Click button *OK*.

The 'Edit WDVS (Zelt & Chen 2016)' dialog box contains the following fields and options:

- use WDVS for forward modeling of traveltimes
- fast WDVS : less accurate mapping of scan line nodes to grid nodes
- add nodes once only with overlapping scan lines for velocity averaging
- add all velocity nodes within WDVS area with radius of one wavelength
- pad WDVS area border with one grid cell
- WDVS frequency: 300.00 [Hz]
- Angle increment between scan lines: 7 [Degree]
- Regard nth node along scan line: 3 [node]
- Parameters for Cosine-Squared weighting function (Chen and Zelt 2012): a: Cosine argument power: 1.000 [power], b: Cosine-Squared power: 1.000 [power]
- Modify WET smoothing mode : discard after forward modeling: discard WET smoothing and WDVS smoothing after modeling, restore WET smoothing and discard WDVS smoothing only
- Buttons: OK, Cancel, Reset

Fig. 20 : select *Model|WDVS Smoothing*. Edit as shown. Check box *discard WET smoothing*. Click *OK* button.

Edit Surfer plot limits

Plot Limits

Plot limits active Use data limits

Min. offset: [m]

Max. offset: [m]

Min. elevation: [m]

Max. elevation: [m]

Min. velocity: [m/sec.]

Max. velocity: [m/sec.]

Plot Scale

Proportional XY Scaling

Page unit centimeter. Uncheck for inch.

X Scale length: [inch]

Y Scale length: [inch]

Color Scale

Adapt color scale

Scale height: [inch]

Velocity interval: [m/sec.]

Coverage interval: [paths/pixel]

Receiver labeling

First station: [station no.]

Station interval: [station no.]

Use station index or station no. offset

OK
Cancel
Reset
Reset to grid
Redisplay grid

Fig. 21 : select Grid/Surfer plot limits. Edit as shown. Adapt *Min. velocity* to 350 m/s. Edit *Max. velocity* to 1,200 m/s. Click *OK* button.

Edit WET Wavepath Eikonal Traveltime Tomography Parameters

Specify initial velocity model

Select

Stop WET inversion after

Number of WET tomography iterations: iterations

or RMS error gets below percent

or RMS error does not improve for n = iterations

or WET inversion runs longer than minutes

WET regularization settings

Wavepath frequency: Hz

Ricker differentiation [-1:Gaussian,-2:Cosine]: times

Wavepath width [percent of one period]: percent

Wavepath envelope width [% of period]: percent

Min. velocity: Max. velocity: m/sec.

Width of Gaussian for one period [SD]: sigma

Gradient search method

Steepest Descent Conjugate Gradient

Conjugate Gradient Parameters

CG iterations: Line Search iters.:

Tolerance: Line Search tol.:

Initial step: Steepest Descent step

Edit WET Tomography Velocity Smoothing Parameters

Determination of smoothing filter dimensions

Full smoothing after each tomography iteration

Minimal smoothing after each tomography iteration

Manual specification of smoothing filter, see below

Smoothing filter dimensions

Half smoothing filter width: columns

Half smoothing filter height: grid rows

Suppress artefacts below steep topography

Adapt shape of filter. Uncheck for better resolution.

Maximum relative velocity update after each iteration

Maximum velocity update: percent

Smooth after each nth iteration only

Smooth nth iteration: n = iterations

Smoothing filter weighting

Gaussian Uniform No smoothing

Used width of Gaussian: [SD]

Uniform central row weight: [1..100]

Smooth velocity update before updating tomogram

Smooth update Smooth nth Smooth last

Damping of tomogram with previous iteration tomogram

Damping [0..1]: Damp before smoothing

Fig. 22 : WET Tomo/Interactive WET main dialog (left). Edit velocity smoothing (right).

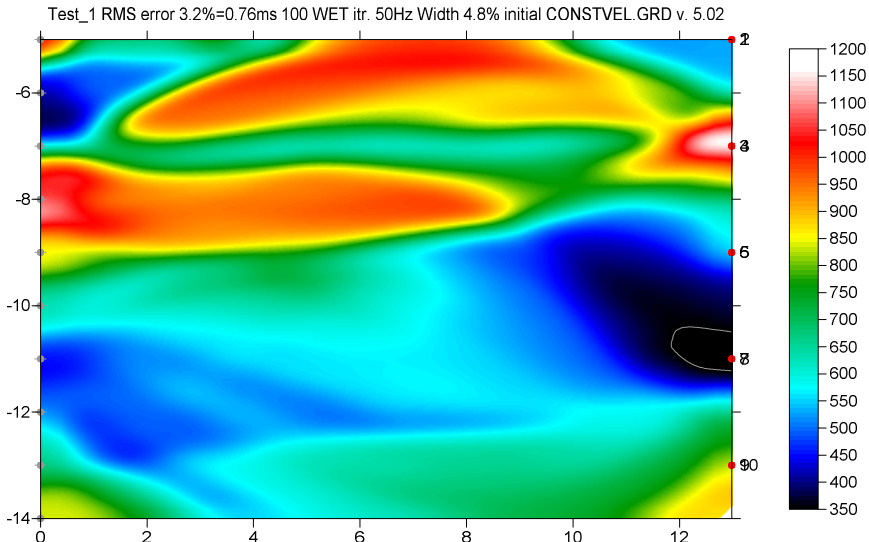


Fig. 23 : WET tomogram obtained with optimized WET (Fig. 22) and WDVS settings (Fig. 20). 100 WET iterations (Fig. 22 left). Discard WET smoothing after forward modeling (Fig. 20). Edit Grid/Surfer plot Limits as in Fig. 21. Constant-velocity starting model shown in Fig. 16.

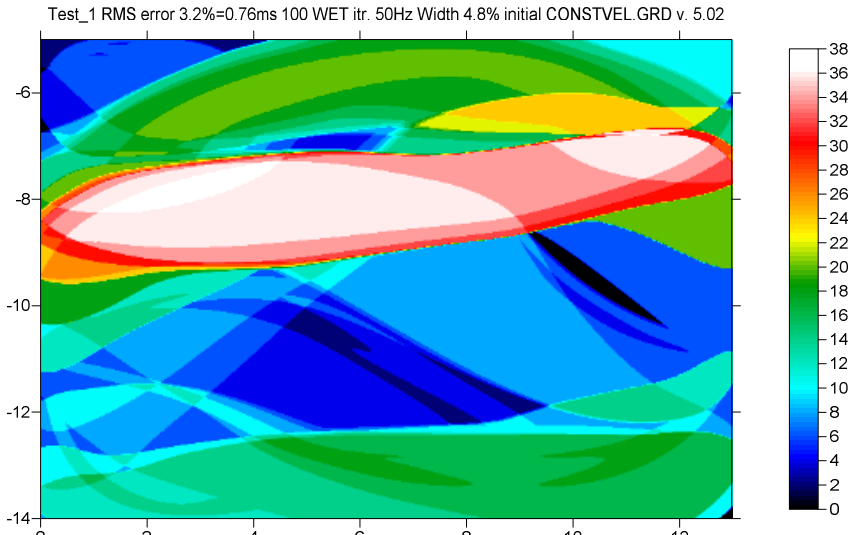


Fig. 24 : WET wavepath coverage plot obtained with Fig. 23. Unit is wavepaths per grid cell.

Fig. 25 : *Header/Shot*. Check if fields x and z in frame *Source Coords. [m]* match the *Source x offset from top-of-hole* and *Source depth below top-of-hole* as specified in SEG2_HoleMerge program (Fig. 5).

Fig. 26 : *Header/Station*. Use F7/F8 keys to browse to *Station position [station no.] -5.0* as referenced in above *Header/Shot* (Fig. 23).

Download the .rar archive of the profile folder obtained with above processing (Fig. 18) from DropBox link

https://www.dropbox.com/scl/fi/0bkz8wr117ayc6k66bcnr/Test_1_Nov16_25.rar?rlkey=699d1h3h02gsn06ht3euei42z&st=1wbz1qmu&dl=0

Here is the DropBox link to .rar archive for profile folder for Fig. 23 :

https://www.dropbox.com/scl/fi/4rz9698iwh2n756xz0nq8/Test_1_Nov18_25.rar?rlkey=giwt1h3wjl1nhl9s04kjl1ma&st=410v5i3z&dl=0

See also our updated 2025 manual

<https://rayfract.com/help/rayfract.pdf>

chapter *Crosshole survey interpretation* and chapter *Downhole VSP interpretation* and chapter *Aggregate AMBROGEO or PASI 3-component borehole geophone channels into SEG-2 borehole spread files*.

See also our VSP tutorial https://rayfract.com/tutorials/PW27_Test.pdf showing P-wave VSP processing and our tutorial https://rayfract.com/tutorials/SH27_Test.pdf showing S-wave shear-wave VSP processing for the same VSP borehole.

See also our 2024 P-wave VSP tutorials <https://rayfract.com/tutorials/TTBM6.pdf> and <https://rayfract.com/tutorials/TTBM4.pdf> and our earlier VSP tutorial <https://rayfract.com/tutorials/vsp.pdf>

See also our crosshole tutorials https://rayfract.com/tutorials/MDW2011_23.pdf and <https://rayfract.com/tutorials/b8b9.pdf>

and our walkaway VSP tutorial <https://rayfract.com/tutorials/walkaway.pdf> .

See also our joint inversion of surface refraction spread with borehole receiver spread tutorial

<https://rayfract.com/tutorials/11REFR.pdf>

and our tutorial with receivers in 3 boreholes <https://rayfract.com/tutorials/KING17.pdf> .

- Doug Crice describes cross-hole and down-hole shear wave recording geometry in his paper http://geostuff.com/Downhole_Shearwaves.pdf
- we allow picking of shear waves on shot traces recorded with reversed shot polarity in our *TraceShot point gather* display. See above and our manual <https://rayfract.com/help/rayfract.pdf> chapter *Shear wave picking* and our borehole shear-wave VSP tutorials https://rayfract.com/tutorials/SH27_Test.pdf and <https://rayfract.com/tutorials/BOATSH26.pdf> .

Discussion

We show gathering of SEG-2 channels recorded with Geotomographie 3-component borehole geophone into SEG-2 receiver spread files sorted by channel number and receiver elevation. ***We assume that the 3-channel receiver trace files are named <receiver_depth><optional wave identifier>.DAT / .SG2 / .SEG2.***

1.DAT / 1HFLeft.DAT / 1HFRight.DAT means the borehole receiver was located at elevation -1m with the borehole top at elevation 0m. HFLeft or HFRight is the wave identifier and stands for “Horizontal force left” or “Horizontal force right” shear-wave source.

30.DAT / 30HFLeft.DAT / 30HFRight.DAT means the borehole receiver was positioned at the elevation of -30m. ***Rename your SEG-2 receiver channel files in Windows Explorer to match this file naming convention.***

Next we import the aggregated SEG-2 borehole receiver spread files into a Rayfract(R) borehole profile database. Next we apply frequency filtering and Automatic Gain Control (AGC) and pick the shear-wave first breaks in *TraceShot point gather*. Next we run our default Smooth inversion to obtain the shear-wave velocity tomogram. Finally we run 100 Steepest-Descent WET iterations (Fig. 22; Schuster 1993) and discard the WET smoothing after forward modeling (Fig. 20) to obtain an optimized WET tomogram with a lower RMS error than obtained with our default Smooth inversion.

Acknowledgements

We thank our anonymous client for making available this interesting crosshole survey. According to the client : “the scope of this project was to use crosshole tomography to investigate Vs under a concrete cap to find evidence of voids. The shallowest shots were likely above the concrete cap, so it makes sense that some of the Vs values would be high.” .

References

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