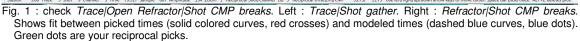


Import SEG-2 .DAT & Update header data & Smooth invert shear wave SH 60M v. 5.01 :



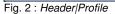
To create the profile database, import the data and browse the imported shots do these steps :

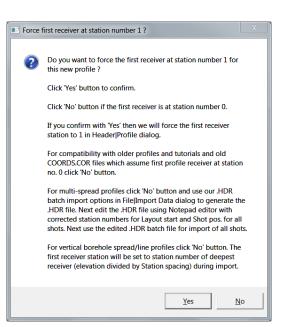
- File New Profile..., set File name to SH_60M and click Save button
- in the prompt shown next (Fig. 4) click Yes button to force Profile start / first channel at station no. 1
- in *Header*|*Profile*... select *Line type* Refraction spread/line . Set *Station spacing* to 2.5 m. See Fig. 2.
- unzip archive https://rayfract.com/tutorials/SH_60M_INPUT.zip with SEG-2 .SG2 shot files & file BREAKS.LST in directory C:\RAY32\SH_60M\INPUT
- select *FileImport Data*... and set *Import data type* to **SEG-2**. See Fig. 3.
- click Select button and navigate into C:\RAY32\SH_60M\INPUT
- set control Files of type to ABEM files (*.SG2) and select a file e.g. ADX.SG2 & click Open
- set control Take shot record number from to File number
- leave Default spread type at 10: 360 channels
- click *Import shots button*.
- leave Layout start at 1 for all shots displayed in our Import shot dialog
- specify *Shot pos. [station no.]* 0.5, 0.5, 24.5, 24.5, 12.5, 12.5, 6.5, 6.5, 18.5, 18.5 and click *Read button* for *Shot Number* 1 to 10
- select File|Update header data|Update First Breaks. Select file BREAKS.LST & click Open.
- select option Trace|Open Refractor|Shot CMP breaks with Shot gather
- select *TracelShot gather* to obtain Fig. 1
- press SHIFT+Q to show Frequency filter dialog. Uncheck Filter active. Click Filter. See Fig. 11.
- click on title bar of *TracelShot gather* window and press CTRL+F1 to zoom trace amplitude
- browse shots in *TracelShot gather* window with F7/F8 (Fig. 1 left)
- click on title bar of *Refractor*|*Shot CMP breaks* window (Fig. 1 right) and press ALT+P. Edit *Maximum time* to 200 ms & press ENTER key to redisplay. Do the same for *Trace*|*Shot gather* window (Fig. 1 left).

Run default fail-safe Smooth inversion with 1D-gradient laterally averaged starting model :

- check option Grid|Receiver station ticks on top axis
- check option *Grid*|*CS_CENTERED font for shot points and receivers* to workaround Surfer symbol display issues
- edit *Grid*|*Surfer plot Limits* as in Fig. 8
- select *Model*|*WDVS Smoothing* and click radio button *restore WET smoothing and discard WDVS smoothing only*. Leave box *use WDVS for forward modeling of traveltimes* unchecked (Fig. 9).
- select Smooth invert|WET with 1D-gradient initial model
- wait for the 1D-gradient starting model to display as in Fig. 5
- confirm prompt to continue with WET inversion to obtain WET output shown in Fig. 6 & 7

dit Profile				
Line ID St	1_60m		Time	of Acquisition
	efraction spream	d/line ×	Date	
Job ID	inaction spread		Time	
Instrument			Time of Date	of Processing
Client			Time	
Company			Time]
Observer	Observer		Units	meters
Note			Sort	As acquired 💌
		-	Const	
Station spacing [m	1	2 50000	Lef	, thanded coordinates
		25		
Min. horizontal separation [%]		0,0000		
Profile start offset [mJ	0.0000		
Force grid cell size		Cel	l size (m)	0.2000
-Force first receiv	er station numb	per for profile		
First receiver [sta	ation number]	1	🔽 Fo	rce first receiver
Extrapolate starti	ing models and	d WET tomogram	ns	
Extrapolate [stati	on spacings]	0	Ext	rapolate tomograms
Add borehole line	es for WET tor	nography		
	Select			
Borehole 1 line				
Borehole 1 line Borehole 2 line	Select			
	Se <u>l</u> ect Select			
Borehole 2 line				





Import shots						
Import data type	SEG-2					
Input directory : select one data file. All data files will be imported						
Select	C:\RAY32\SH_60m\INPUT\					
Take shot record number from File number						
Optionally select .HDR batch file and check Batch import						
.HDR batch						
Write .HDR batch file listing shots in input directory						
Write HDR only	Import shots and write .HDR					
Overwrite existing shot data —	Batch import					
Overwrite all OPrompt	overwriting					
Maximum offset imported [station	nos.] 1000.00					
Default shot hole depth [m]	Default spread type					
0.00	10: 360 channels 🔹					
Target Sample Format	16-bit fixed point					
Turn around spread during in						
Default sample interval [msec]	0.100000000 Force sample interval					
Default sample count	20000 Force sample count					
Import shots	ancel import <u>R</u> eset import					

Fig. 3 : File/Import Data

Fig. 4 : click *Yes* button to force the first receiver at station number 1 for this profile.

For compatibility with older profiles and tutorials and old COORDS.COR files which assume first profile receiver at station no. 0 click No button. For multi-spread profiles click No button and use our .HDR batch import options in *File/Import Data* dialog to generate the .HDR file. Next edit the .HDR file using MS Notepad editor with corrected station numbers for *Layout start* and *Shot pos.* for all shots. Next use the edited .HDR batch file for import of all shots.

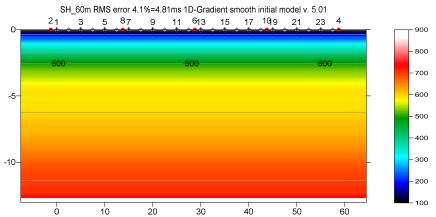


Fig. 5 : 1D-gradient starting model obtained with Smooth invert/WET with 1D-gradient initial model.

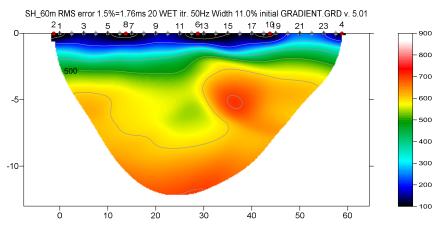
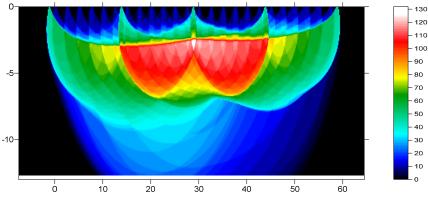


Fig. 6 : 2D WET output obtained with *Smooth invert/WET with 1D-gradient initial model* & starting model shown in Fig. 5. 20 WET iterations using Steepest Descent method & Gaussian update weighting & full WET smoothing. Don't discard WET smoothing after forward modeling. Leave WDVS disabled (Fig. 9).



SH_60m RMS error 1.5%=1.76ms 20 WET itr. 50Hz Width 11.0% initial GRADIENT.GRD v. 5.01

Fig. 7 : WET wavepath coverage plot obtained with Fig. 6. Unit is wavepaths per grid cell.

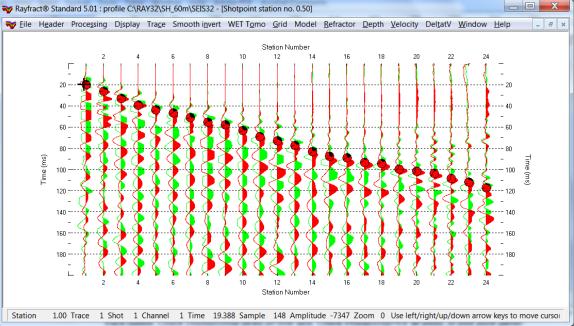
Edit Surfer plot limits	
Plot Limits OK ✓ Plot limits active Use data limits Min. offset -7.500 [m] Cancel Max. offset 64.500 [m] Reset Min. elevation -13.000 [m] Reset to grid	Fig. 8 (left) : <i>Grid Surfer plot Limits</i> dialog . Edit WDVS (Zelt & Chen 2016) Edit parameters for wavelength-dependent velocity smoothing
Max elevation 0.000 [m] Redisplay grid Min. velocity 100 [m/sec.] Max velocity 900 [m/sec.] Plot Scale Proportional XY Scaling Page unit centimeter. Uncheck for inch. X Scale length X Scale length 6.000 [inch] Y Scale length 3.000 [inch] Color Scale [or Adapt color scale Scale height 3.125 [inch] Velocity interval 100 [m/sec.] Coverage interval 10 [paths/pixel] Receiver labeling [istation no.] Station interval 2 [station no.] Use station index or station no. offset	□use WDVS for forward modeling of traveltimes □ fast WDVS : less accurate mapping of scan line nodes to grid nodes □ add nodes once only with overlapping scan lines for velocity averaging □ add nodes once only with overlapping scan lines for velocity averaging □ add all velocity nodes within WDVS area with radius of one wavelength □ pad WDVS area border with one grid cell WDVS frequency 300.00 Angle increment between scan lines 7 □ Parameters for Cosine-Squared weighting function (Chen and Zelt 2012) a: Cosine argument power 1.000 □ Power] b: Cosine-Squared power 1.000 □ Modify WET smoothing mode : discard after forward modeling □ discard WET smoothing and WDVS smoothing after modeling □ OK Cancel ■ Reset

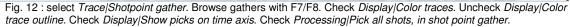
Select	error file		C:\RAY32\SH_60M\RECIPROCAL.E
Sort lines in .	ERR file by decre	asing reciprocal	error
C Sort.EF	R lines by relative	e reciprocal erroi	r -
C Sort.EF	R lines by absolu	te reciprocal err	or in ms
G Sort.EF	R lines by offset a	and CMP (as in T	race Offset gather display)
		102	
CMP interva	for mapping com	mon-offset sorte	d traces to same midpoint

Fig. 10 : Trace/Export reciprocal errors and update database

Frequency filter : band-pass or band-reject					
Filter active for current trace gather display Filter active for current trace gather display Filter Band-pass filter. Uncheck for band-reject. Filter active filter Batter preserve circled					
 Bidirectional filter. Better preserve signal. Chebyshev filter. Uncheck for single-pole. 					
Apply n times [n]	1				
Low corner frequency [Hz]	50.00				
High corner frequency [Hz]	50.00				
Percent ripple [%]	0.0				
Number of poles [n]	2				
Filter Cancel	Reset				

Fig. 11 : press SHIFT+Q in *Trace/Shot gather*. Uncheck box *Filter active for current trace gather display*. Click button *Filter*.





Pick shear-wave first breaks in TracelShotpoint gather display

- ▶ select *TracelShotpoint gather*. Browse gathers with F7/F8. See Fig. 12.
- ➤ check Display|Color traces. Uncheck Display|Color trace outline.
- check Display|Show picks on time axis.
- > check *Processing*|*Pick all shots, in shot point gather.*
- > press SHIFT+Q. Uncheck box *Filter active*. Click button *Filter*. See Fig. 11.
- > pick S-wave first breaks with left mouse button. See Fig. 12. Solid red circles are your picks.
- ▶ select *File Export header data Export First Breaks to .LST*. Click *Save* to save to **BREAKS**.LST.

Plot your reciprocal traveltime picks on shot-sorted trace gathers :

Plotting your reciprocal traveltime picks on shot-sorted trace gathers lets you quality-control your first break picks and check the validity of your recording geometry specification (shot station numbers and receiver station numbers):

- > select *Trace Export reciprocal traveltime picks and update database*
- > click button Select error file and click Save button (Fig. 10)
- click button Export to .ERR
- > optionally check new option TracelOpen Refractor|Shot CMP breaks with Shot gather
- ▶ select *TracelShot gather* to obtain a window display as in our Fig. 1
- > check new version 4.05 option Display|Show reciprocal picks on Shot Gather
- browse and zoom trace gathers with function keys F7/F8, F1/F2 etc. as usual
- > navigate traces with arrow-left and arrow-right keys
- if a reciprocal pick was determined/matched to the current trace then this is plotted as a green dot on the trace
- also we show *Reciprocal Shot/Channel* and *Reciprocal offset[m]/CMP* in status bar at bottom of window (Fig. 1 left) if a reciprocal pick is available in the .ERR file

Here is the link to the .RAR archive with the SH_60M profile folder for above Fig. 6 :

https://www.dropbox.com/scl/fi/vjqy70ux4lhf4vcrnh5lt/SH_60m_Oct5_2024_DisableWDVS.rar?rlkey=m_x0qhf3bls3tik96jxwqdr3t7&st=dw630das&dl=0_

Select above link and copy with CTRL+C. Then paste the link into your web browser with CTRL+V and press RETURN key to download the .RAR archive.

Interactive WET tomography using default fail-safe 1D-gradient starting model

Next we show interactive WET tomography (Fig. 13) using the same 1D-gradient starting model obtained with *Smooth invert*|*WET with 1D-gradient initial model* as shown in Fig. 5. We discard WET smoothing after forward modeling (Fig. 16) trying to reach a better resolution. We increase the number of *WET iterations* from default 20 iterations to 50 iterations. Also we modify the *Ricker differentiation* from default -1 [Gaussian] to 0 [Ricker wavelet] to better deal with the velocity inversion at depth of about 8m (Fig. 6).

Edit WET Wavepath Eikonal Traveltime Tomography Parameters	Edit WET Tomography Velocity Smoothing Parameters		
Specify initial velocity model	Determination of smoothing filter dimensions		
Select C:\RAY32\SH_60m\GRADTOMO\GRADIENT.GRD	Full smoothing after each tomography iteration		
Stop WET inversion after	C Minimal smoothing after each tomography iteration		
Number of WET tomography iterations : 50 iterations	C Manual specification of smoothing filter, see below		
	Smoothing filter dimensions		
	Half smoothing filter width : 21 columns		
or RMS error does not improve for n = 20 iterations	Half smoothing filter height : 3 grid rows		
or WET inversion runs longer than 100 minutes	gird rows		
WET regularization settings	Suppress artefacts below steep topography		
Wavepath frequency : 50.00 Hz Iterate	Adapt shape of filter. Uncheck for better resolution.		
Ricker differentiation [-1:Gaussian,-2:Cosine] : 0 times	Maximum relative velocity update after each iteration		
Wavepath width [percent of one period] : 11.0 percent Iterate	Maximum velocity update : 25.00 percent		
Wavepath envelope width [% of period] : 0.0 percent	Smooth after each nth iteration only		
Min. velocity : 10 Max. velocity : 6000 m/sec.	Smooth nth iteration : n = 1 iterations		
Width of Gaussian for one period [SD]: 3.0 sigma	Smoothing filter weighting		
Gradient search method	C Gaussian 💿 Uniform 🦳 No smoothing		
Steepest Descent Conjugate Gradient	Used width of Gaussian 1.0 [SD]		
Conjugate Gradient Parameters	Uniform central row weight 1.0 [1100]		
CG iterations 10 Line Search iters. 2	Smooth velocity update before updating tomogram		
Tolerance 0.001 Line Search tol. 0.0010	Smooth update Smooth nth 🔽 Smooth last		
Initial step 0.10 Steepest Descent step	Damping of tomogram with previous iteration tomogram		
Edit velocity smoothing Edit grid file generation	Damping [01] 0.000 Damp before smoothing		
Start tomography processing Reset Cancel	Accept parameters Reset parameters		

Fig. 13: WET Tomo/Interactive WET main dialog (left). Edit as shown. Click Edit velocity smoothing (right). Leave at default Full smoothing and click Accept parameters. Click Start tomography processing to obtain Fig. 14 and 15.

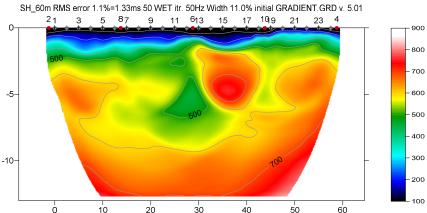


Fig. 14 : 50 Steepest-Descent WET iterations using a Ricker wavelet for weighting of WET velocity update across the wavepath (Fig. 13 left). Leave WET smoothing at default *Full smoothing* (Fig. 13 right). Starting model is Fig. 5. Discard WET smoothing (Fig. 16).

In Fig. 14 we reach a smaller RMS error compared to Fig. 6. Also the velocity inversion at depth of about 8m becomes better visible.



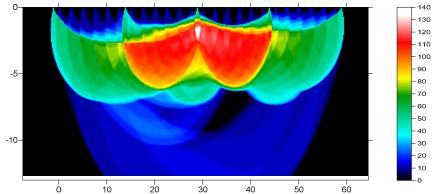


Fig. 15 : WET wavepath coverage plot obtained with Fig. 14. Unit is wavepaths per grid cell.

Edit WDVS (Zelt & Chen 2016)						
Edit parameters for wavelength-dependent velo	city smoothing-					
use WDVS for forward modeling of traveltimes						
$\overleftarrow{}$ fast WDVS : less accurate mapping of scan line nodes to grid nodes						
$\overleftarrow{}$ add nodes once only with overlapping scan lines for velocity averaging						
add all velocity nodes within WDVS area with radius of one wavelength						
pad WDVS area border with one grid cell						
WDVS frequency	300.00					
	500.00	[Hz]				
Angle increment between scan lines	7	[Degree]				
Regard nth node along scan line	3	[node]				
Parameters for Cosine-Squared weighting function	on (Chen and Ze	elt 2012)				
a : Cosine argument power	1.000	[power]				
b : Cosine-Squared power	1.000	[power]				
─Modify WET smoothing mode : discard after forw	ard modeling-					
 discard WET smoothing and WDVS smoothing after modeling 						
C restore WET smoothing and discard WDVS	smoothing only					
OK Cancel Reset						

Fig. 16 : *Model/WDVS Smoothing*. Check option Discard WET smoothing and WDVS smoothing after modeling. Click OK button.

Here is the link to the .RAR archive with the SH_60M profile folder for above Fig. 14 :

https://www.dropbox.com/scl/fi/7pt1naxzdeekpeh2f17kt/SH 60m GradTomo 50WETIters RickerDiff0 Oct13_2024.rar?rlkey=tq1t20738dg9ly381zpl9vjsf&st=8gmu4vjy&dl=0

Smooth invert using 1D-gradient starting model and discarding WET smoothing

Next we show re-running our Smooth invert using the same 1D-gradient starting model shown in Fig. 5. But now we discard the WET smoothing as shown in Fig. 16 :

- select Model WDVS Smoothing
- > check option *Discard WET smoothing* (Fig. 16) and click button OK.
- select Smooth invert|WET with 1D-gradient initial model
- ➤ wait for the same 1D-gradient starting model to display as in Fig. 5
- > confirm prompt to continue with WET inversion to obtain refined WET output shown in Fig. 17 & 18

SH_60m RMS error 1.4%=1.60ms 20 WET itr. 50Hz Width 11.0% initial GRADIENT.GRD v. 5.01 21 3 5 87 9 11 613 15 17 19 21 23 4

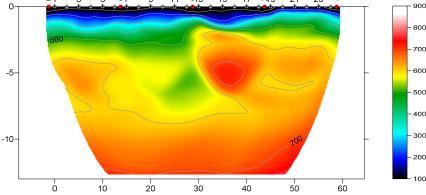
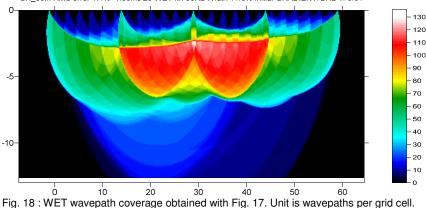


Fig. 17 : 2D WET output obtained with *Smooth invert/WET with 1D-gradient initial model* & starting model shown in Fig. 5. 20 WET iterations using Steepest Descent method & Gaussian update weighting & full WET smoothing. Discard WET smoothing after forward modeling. Leave WDVS disabled (Fig. 16).



SH_60m RMS error 1.4%=1.60ms 20 WET itr. 50Hz Width 11.0% initial GRADIENT.GRD v. 5.01

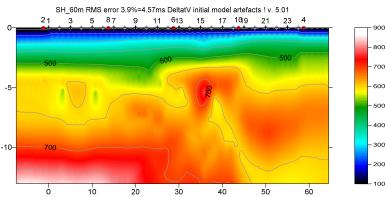
Here is the link to the .RAR archive with the SH_60M profile folder for above Fig. 17 :

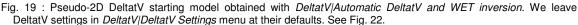
https://www.dropbox.com/scl/fi/ku4os7jrb1j1gn5epsehk/SH_60m_GradTomo_SmoothInvert_DiscardWET_ Oct18_2024.rar?rlkey=ufm7of2fyvltoe2vibg2pwqx0&st=9u3x7zdd&dl=0

Smooth invert using pseudo-2D DeltatV starting model and discarding WET smoothing

Next we show running our Automatic DeltatV and WET inversion using the pseudo-2D DeltatV starting model shown in Fig. 19. We again discard the WET smoothing as shown in Fig. 16 :

- select Model WDVS Smoothing
- > check option *Discard WET smoothing* (Fig. 16) and click button OK.
- ➢ select DeltatV\Automatic DeltatV and WET inversion
- wait for the pseudo-2D DeltatV starting model to display as in Fig. 19
- confirm prompt to continue with WET inversion to obtain WET output shown in Fig. 20 & 21





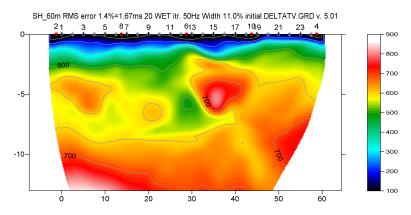
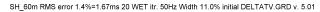


Fig. 20 : 2D WET output obtained with *DeltatV/Automatic DeltatV and WET inversion* & starting model shown in Fig. 19. 20 WET iterations using Steepest Descent method & Gaussian update weighting & full WET smoothing. Discard WET smoothing after forward modeling. Leave WDVS disabled (Fig. 16). We leave DeltatV settings in *DeltatV/DeltatV Settings* menu at their defaults. See Fig. 22.



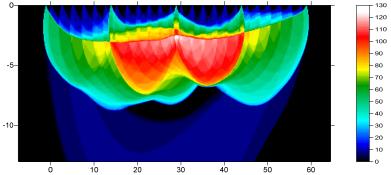


Fig. 21 : WET wavepath coverage plot obtained with Fig. 20. Unit is number of wavepaths per grid cell.

	Output Measured CMP Velocities
\checkmark	Output Horizontal offset of CMP pos. in meters
	Output DeltatV results in Feet
	Allow regression over two CMP traces
✓	CMP is zero time trace
\checkmark	Reduced offset 0.0 is valid trace with time 0.0
	Enforce Monotonically increasing layer bottom velocity
	Suppress velocity artefacts
	Process every CMP offset
\checkmark	Prefer Average over minimum interface velocity
	Taper velocity steps at layer interfaces
	Smooth CMP traveltime curves
✓	Weigh picks in CMP curves
	Extrapolate output to all receivers
	Regard mapping for shot offset correction
	Regard true receiver coordinates for shot offset correction
	Regard 3D source-receiver offset for all traces
	Extrapolate tomogram over 30 station spacings
	Extra-large cell size
	Increase cell size
	Decrease cell size
	Extra-small cell size
	Edit cell size
	Limit DeltatV velocity exported to maximum 1D-gradient velocity
	Limit DeltatV velocity exported to 5,000 m/s
	Write new DeltatV settings to .PAR file
	Reset DeltatV settings to default
	Reset DeltatV and WET and WDVS settings to .PAR file

Fig. 22 : DeltatV/DeltatV Settings. Leave settings at their defaults as shown.

Note the good match between the pseudo-2D DeltatV starting model in Fig. 19 and the resulting 2D WET tomogram in Fig. 20. Also note the good match between Fig. 20 and Fig. 17 using our fail-safe 1D-gradient starting model.

Pseudo-2D DeltatV fails to give a realistic starting model in case of strong topography or with strong lateral velocity change in the overburden. See e.g. our tutorial <u>https://rayfract.com/tutorials/1_1D.pdf</u>. Always first run our Smooth invert as shown above in Fig. 6 using our fail-safe 1D-gradient starting model obtained by laterally averaging 1D DeltatV velocity profiles (Fig. 5; Sheehan 2005).

Here is the link to the .RAR archive with the SH_60M profile folder for above Fig. 20 :

https://www.dropbox.com/scl/fi/junrcad5tcdg22bi5mxg4/SH_60m_DeltatV_And_WET_Nov3_2024.rar?rl key=ft5eh9ujo833pnrp3b8tx3ny7&st=rpcgpnrx&dl=0

Multiscale WET inversion using 1D-gradient starting model and discarding WET smoothing

Next we run our *multiscale WET inversion* to further improve the resolution in the WET tomogram. We use the same *fail-safe 1D-gradient starting model* shown in Fig. 5. We again discard the WET smoothing as shown in Fig. 16. We edit the *Surfer plot Limits* to better visualize the velocity inversion. We enable scaling of *WET wavepath width* and *WET filter height*. We use proven default settings in *WET TomolInteractive WET* dialog and default WET smoothing :

- select Model WDVS Smoothing
- check option Discard WET smoothing (Fig. 16) and click button OK.
- select Smooth invert|WET with 1D-gradient initial model
- ▶ wait for the same 1D-gradient starting model to display as in Fig. 5
- > confirm prompt to continue with WET inversion to obtain refined WET output shown in Fig. 17 & 18
- ▶ edit *Grid*|*Surfer plot Limits* as in Fig. 23. Click button *OK*.
- uncheck option WET Tomo\Blank\Blank below envelope after last iteration
- ▶ uncheck WET Tomo|WET tomography Settings|Disable wavepath scaling for short profile (Fig. 24).
- select WET TomolInteractive WET. Edit main dialog and WET smoothing as in Fig. 25 : reset parameters to their defaults.
- ▶ in WET TomolInteractive WET main dialog click Iterate button. Leave settings at defaults (Fig. 26).
- > check box WET runs active (Fig. 26). Click OK button. Click button Start tomography processing.

Edit Surfer plot limit	s		
Plot Limits			ок
Plot limits active	🗌 Use	data limits	
Min. offset	-7.500	[m]	Cancel
Max. offset	64.500	[m]	Reset
Min. elevation	-13.000	[m]	Reset to grid
Max. elevation	1.000	[m]	Redisplay grid
Min. velocity	100	[m/sec.]	
Max. velocity	1000	[m/sec.]	
Plot Scale Proportional XY Page unit centim	-	for inch.	
X Scale length	6.000	[inch]	
Y Scale length	3.000	[inch]	
- Color Scale			
Adapt color scal	e		
Scale height	3.125	[inch]	
Velocity interval	100	[m/sec.]	
Coverage interval	10	[paths/pixel]	
Receiver labeling			
First station	1	[station no.]	
Station interval	2	[station no.]	
Use station inde	x or station no	offset	

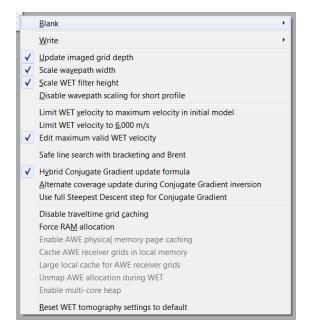


Fig. 24 : WET Tomo/WET tomography Settings. Uncheck Disable wavepath scaling for short profile to enable scaling of wavepath width and WET filter height.

Fig. 23 : Grid/Surfer plot Limits

Edit WET Wavepath Eikonal Traveltime Tomography Parameters	Edit WET Tomography Velocity Smoothing Parameters		
Specify initial velocity model	Determination of smoothing filter dimensions		
Select C:\RAY32\SH_60m\GRADTOMO\GRADIENT.GRD	Full smoothing after each tomography iteration		
Stop WET inversion after	Minimal smoothing after each tomography iteration		
Number of WET tomography iterations : 20 iterations	C Manual specification of smoothing filter, see below		
or RMS error gets below 2.0 percent	Smoothing filter dimensions		
or RMS error does not improve for n = 20 iterations	Half smoothing filter width : 21 columns		
	Half smoothing filter height : 3 grid rows		
or WET inversion runs longer than 100 minutes			
WET regularization settings	Suppress artefacts below steep topography		
Wavepath frequency : 50.00 Hz Iterate	Adapt shape of filter. Uncheck for better resolution.		
Ricker differentiation [-1:Gaussian,-2:Cosine] : -1 times	Maximum relative velocity update after each iteration		
Wavepath width [percent of one period]: 11.0 percent Iterate	Maximum velocity update : 25.00 percent		
Wavepath envelope width [% of period] : 0.0 percent	Smooth after each nth iteration only		
Min. velocity : 10 Max. velocity : 6000 m/sec.	Smooth nth iteration : n = 1 iterations		
Width of Gaussian for one period [SD] : 3.0 sigma	Smoothing filter weighting		
Gradient search method	◯ Gaussian		
Gradient search method Conjugate Gradient	Used width of Gaussian 1.0 [SD]		
Conjugate Gradient Parameters	Uniform central row weight 1.0 [1100]		
CG iterations 10 Line Search iters. 2	Smooth velocity update before updating tomogram		
Tolerance 0.001 Line Search tol. 0.0010	Smooth update Smooth nth 🔽 Smooth last		
Initial step 0.10 Steepest Descent step	Damping of tomogram with previous iteration tomogram		
Edit velocity smoothing Edit grid file generation	Damping [01] 0.000 Damp before smoothing		
Start tomography processing Reset Cancel	Accept parameters Reset parameters		

Fig. 25 : select WET Tomo/Interactive WET. Click Reset in main dialog (left). Click button Edit velocity smoothing. Click button Reset parameters (right). Click button Accept parameters. Click button Iterate. Edit as in Fig. 26.

Run No.	Freg. [Hz]	Width [%]	Width [ms]	Iterations		
Run 1	50.0	30.0	6.000	20	Blank	ОК
Run 2	50.0	26.0	5.200	20	Blank	Cancel
Run 3	50.0	22.0	4.400	20	🔲 Blank	Reset
Run 4	50.0	18.0	3.600	20	Blank	✓ WET runs active
Run 5	50.0	15.0	3.000	20	🔲 Blank	Scale default widths
Run 6	50.0	12.0	2.400	20	Blank	Plot runs in Surfer
Run 7	50.0	10.0	2.000	20	Blank	Prompt run misfit
Run 8	50.0	8.0	1.600	20	🔽 Blank	Runs completed
Run 9	50.0	7.0	1.400	0	🔽 Blank	Current run no.
Run 10	50.0	6.0	1.200	0	🔽 Blank	Resume current run
	elow wavep ink after eac	an a	e Blank after	lastrun		

Fig. 26 : *Edit WET runs* dialog for Multiscale WET inversion. Check box *WET runs active*. Click button *OK*.

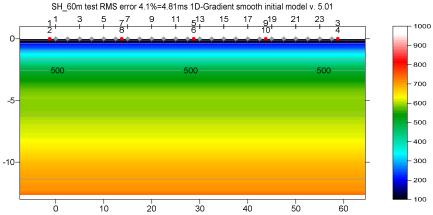


Fig. 27 : 1D-gradient starting model obtained with Smooth invert/WET with 1D-gradient initial model. Same as Fig. 5.

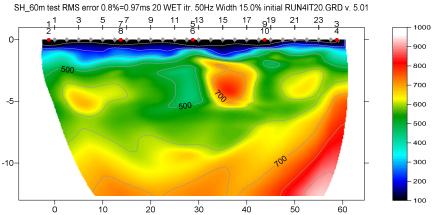
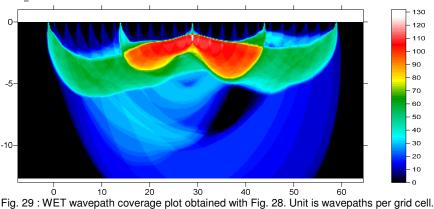


Fig. 28 : WET output after 5 WET runs. Scale WET wavepath width and WET filter height (Fig. 24). Discard WET smoothing after forward modeling (Fig. 16). Default WET Tomo/Interactive WET settings and default WET smoothing (Fig. 25). Enable multiscale WET inversion (Fig. 26). Starting model for first WET run is Fig. 27.





Here is the link to the .RAR archive with the SH_60M profile folder for above Fig. 28 :

https://www.dropbox.com/scl/fi/nqepgn9ybio1k89lnjk31/SH 60m Multiscale WET Nov10 2024.rar?rlke y=0gee5zhhvo7ts8iyjs4esl8p4&st=293msux2&dl=0

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