

Stillwater Model Dam line D1P2NO24 P-wave refraction, 100 WET iterations @30Hz using wavepath width 30 percent and Ricker wavelet for back-projection of residuals

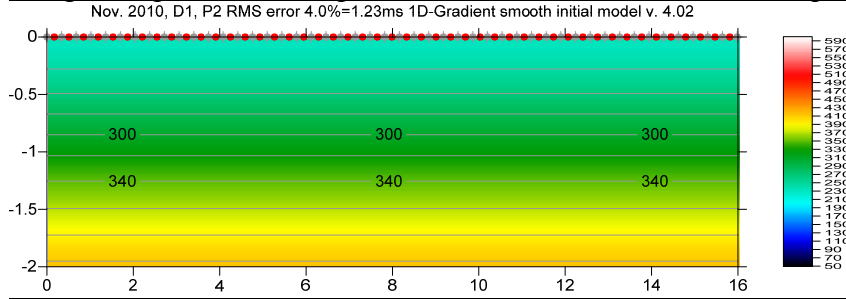


Fig. 1 : 1D-gradient starting model obtained with *Smooth invert|WET with 1D-gradient initial model*. Default settings. *Grid cell size forced to 0.04m in Header|Profile* (Fig. 7). Red circles are sources. Grey symbols are geophones.

Nov. 2010, D1, P2 RMS error 3.1%=0.95ms 100 WET itr. 30Hz Width 30.0% initial GRADIENT.GRD v. 4.02

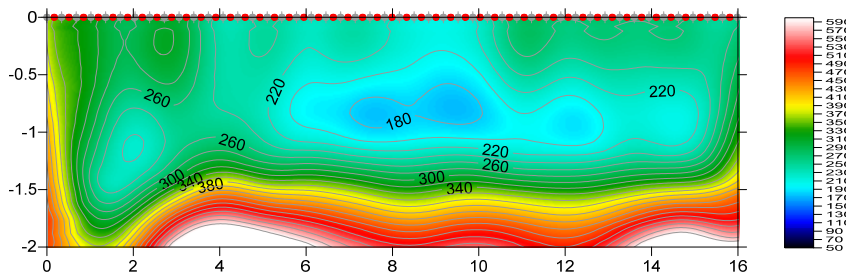


Fig. 2 : 100 WET iterations, WET frequency 30Hz, Wavepath width 30%. Starting model is Fig. 1. Ricker differentiation 0. Minimal WET smoothing. Don't adapt shape of filter. See Fig. 5. No WDVS smoothing.

Nov. 2010, D1, P2 RMS error 3.0%=0.94ms 100 WET itr. 30Hz Width 30.0% initial GRADIENT.GRD v. 4.02

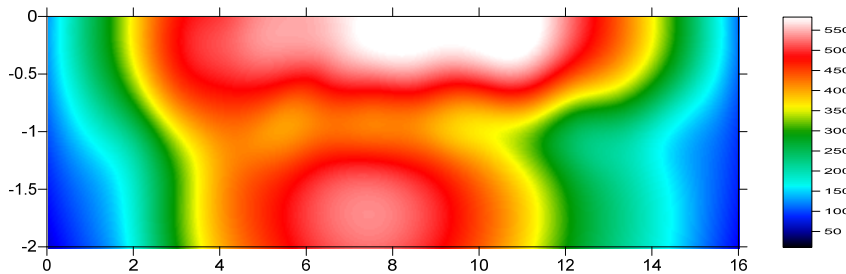


Fig. 3 : WET wavepath coverage plot obtained with Fig. 2. Unit is summed wavepath weight squared. Wavepath coverage plot is sharpened with *Raise wavepath weight to power = 2.0*. See Fig. 8.

Nov. 2010, D1, P2 RMS error 3.0%=0.94ms 100 WET itr. 30Hz Width 30.0% initial GRADIENT.GRD v. 4.02

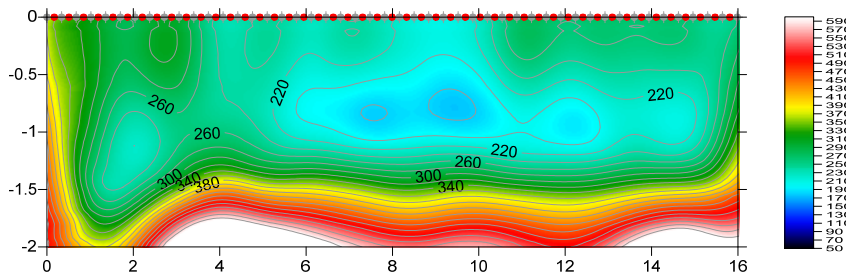


Fig. 4 : Same WET inversion as Fig. 2 but with WDVS smoothing activated @600Hz (Fig. 6).

We reprocessed the original data used for Stillwater Model Dam Fig. 3.13 in PhD Thesis Leti Wodajo ([Wodajo, 2018](#)) to better image two constructed low-velocity regions in the dam.

Compare our optimized interpretation in Fig. 4 with Fig. 3.13 ([Wodajo, 2018](#)). While Fig. 3.13 was obtained with default *WET frequency* 50Hz and default *wavepath width* 5%, we lowered the WET frequency to 30Hz and increased the wavepath width to 30% (Fig. 5). Also we changed the *Ricker differentiation* from default -1 (Gaussian) to 0 (Ricker wavelet; [Schuster 1993](#)).

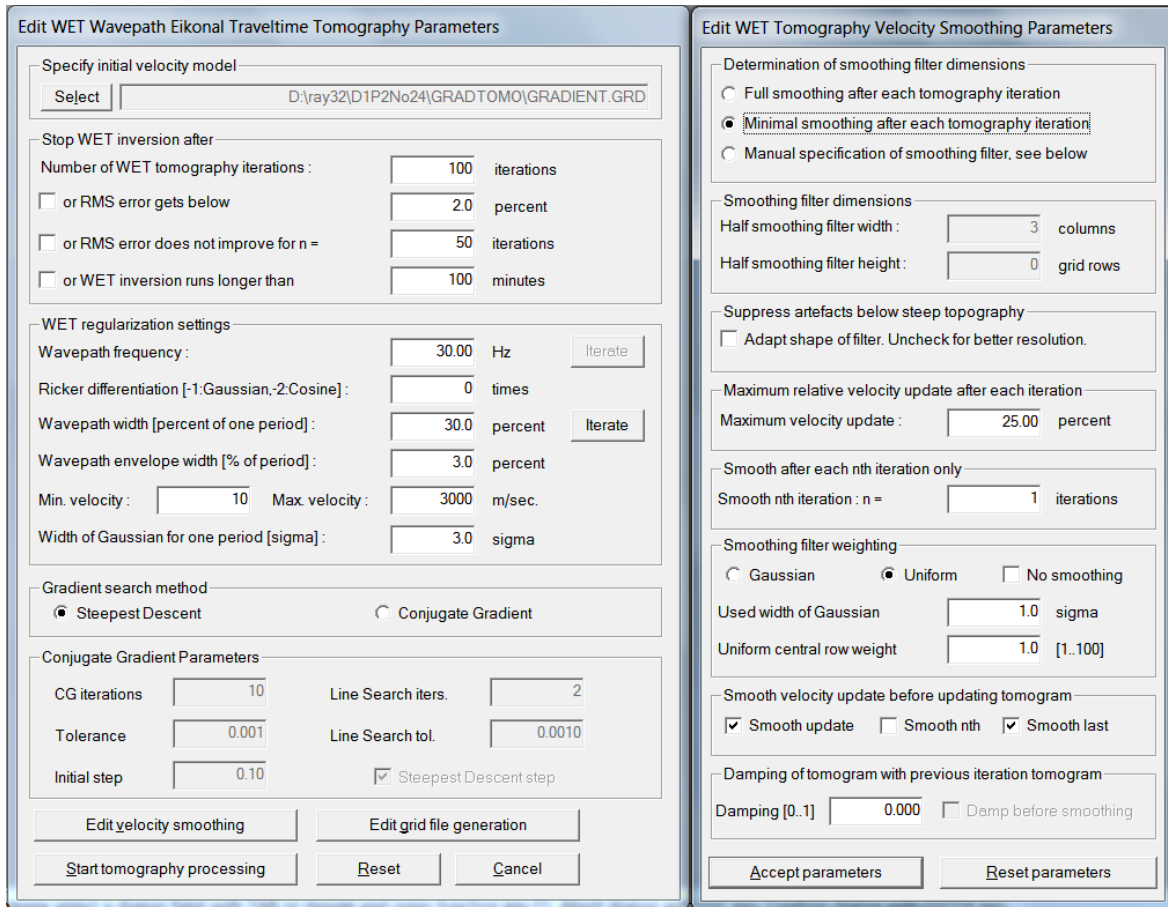


Fig. 5 : WET Tomo|Interactive WET main dialog (left). Edit velocity smoothing (right).

We sharpened the *Wavepath coverage plot* (Fig. 3) with *Raise wavepath weight to power* = 2.0 (Fig. 8) to optimally visualize and match low-velocity anomalies (Fig. 2 and Fig. 4) on the coverage plot.

We used the default 1D-gradient starting model (Fig. 1) obtained by laterally averaging the Deltav pseudo-2D velocity (Sheehan, 2005). We used optimized WET inversion settings and smoothing as in Fig 5. When enabling *Wavelength-Dependent Velocity Smoothing* (WDVS; Zelt and Chen 2016; Rohdewald, 2021a; Rohdewald, 2021b) at 600Hz (Fig. 6) for WET inversion the two central low-velocity zones get separated horizontally more clearly (Fig. 4).

We set *Ricker differentiation* to 0 (Fig. 5) using a Ricker wavelet for weighting of WET velocity update across the wavepath during back-projection of residuals (Schuster, 1993). Ricker wavelet weighting works better than default Gaussian update weighting (Ricker differentiation = -1) for this line.

Before running our WET inversion (Fig. 5) also check option *Model|Forward modeling Settings|Normalize RMS error with maximum picked time* to be compatible with RMS error display on top of Fig. 3.13 (Wodajo, 2018) obtained with version 3.20 of our software.

For this line we observed that the lower the WET *Wavepath frequency* and the wider the WET *Wavepath width* (Fig. 5) the deeper the low-velocity zone in center of tomogram is imaged. This *dependence of imaged anomaly depth on WET wavepath frequency and width* confirms that you need a-priori information about the depth of low-velocity zones for optimal interpretation with our WET inversion (Wodajo, 2018). Also this dependence on WET parameters reconfirms that SRT interpretation is non-unique especially in case of decreasing velocity with increasing depth.

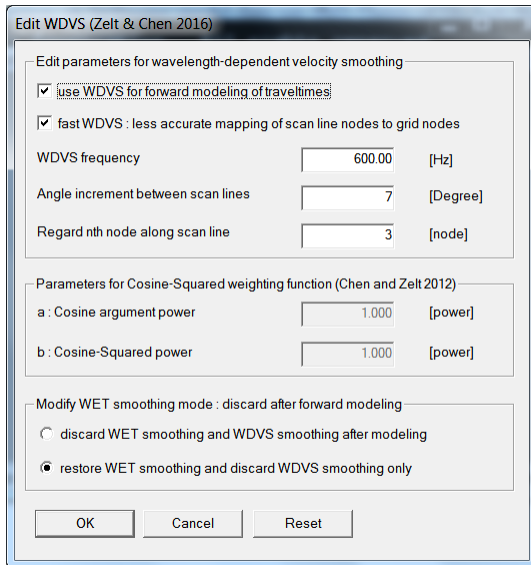


Fig. 6 : Model|WDVS Smoothing

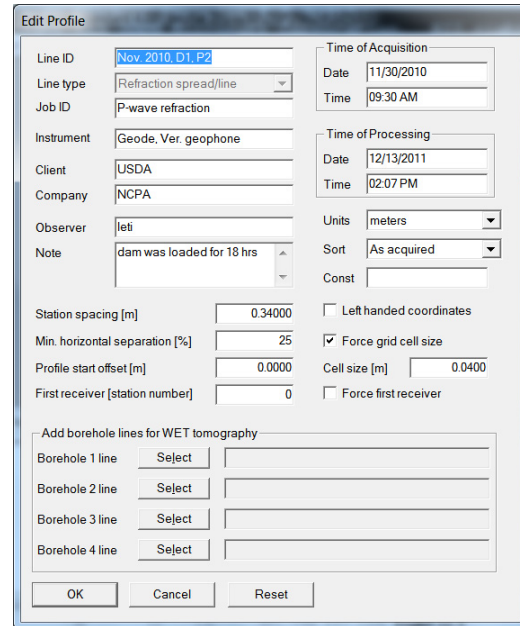


Fig. 7 : Header|Profile

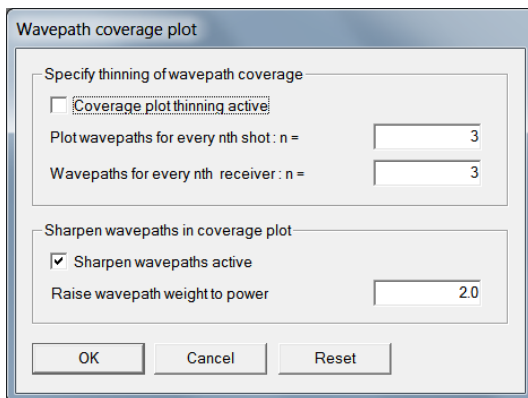


Fig. 8 : WET Tomo|Coverage plot setup

The profile database is available at https://rayfract.com/tutorials/D1P2No24_seis32_50ms_July21_2021.rar

- download above .rar archive to your hard disk
- open Windows Explorer
- navigate into your download directory
- select the .rar archive with left mouse button
- right-click the selected .rar archive and select "Copy" command
- in Windows Explorer navigate into your C:\RAY32 root directory
- click "New folder" and create a new directory C:\RAY32\D1P2NO24
- navigate into this new folder by left-clicking it
- paste above .rar archive with "Paste" command in Windows Explorer "Organize" menu
- right-click the .rar archive in your C:\RAY32\D1P2NO24 directory and select "Extract here" command
- start up Rayfract® via desktop icon
- select **File|Open Profile** and C:\RAY32\D1P2NO24\SEIS32.DBD
- see our [download instructions](#) for details on usage of Windows Explorer and how to get started with our tutorials.

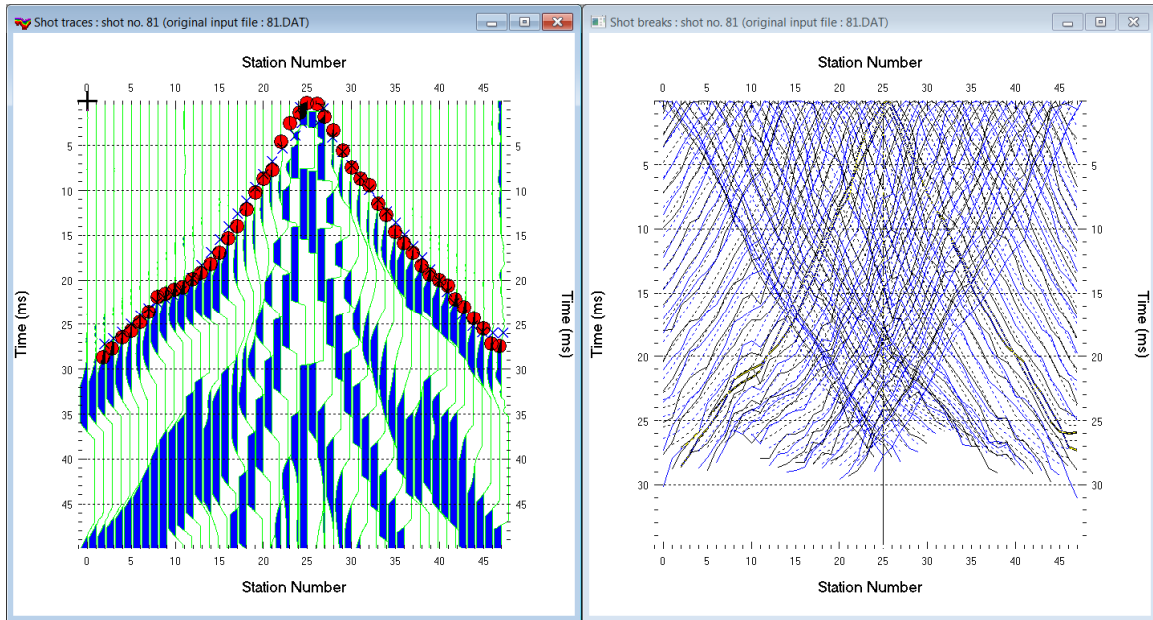


Fig. 9 : *Trace|Shot gather* (left). Red circles are picked first breaks. Blue crosses are modeled first breaks. *Refractor|Shot breaks* (right). Solid grey&blue curves are picked traveltimes. Dashed blue curves are modeled times.

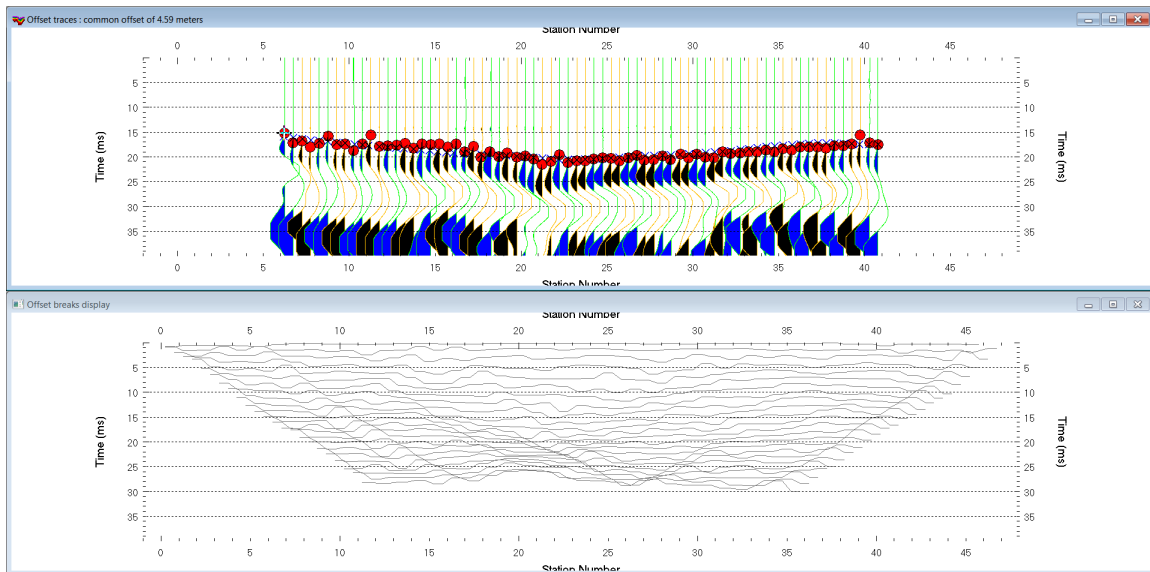


Fig. 10 : *Trace|Offset gather* for common offset of 4.59 meters (top). *Refractor|Offset breaks* (bottom).

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Acknowledgements

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